

# **Resolving the Interactions between the Balance of Plant, SOFC, Power-Conditioning, and Application Loads**

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**SECA Core Technology Program Review Meeting**

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Boston, Massachusetts

**University of Illinois at Chicago**

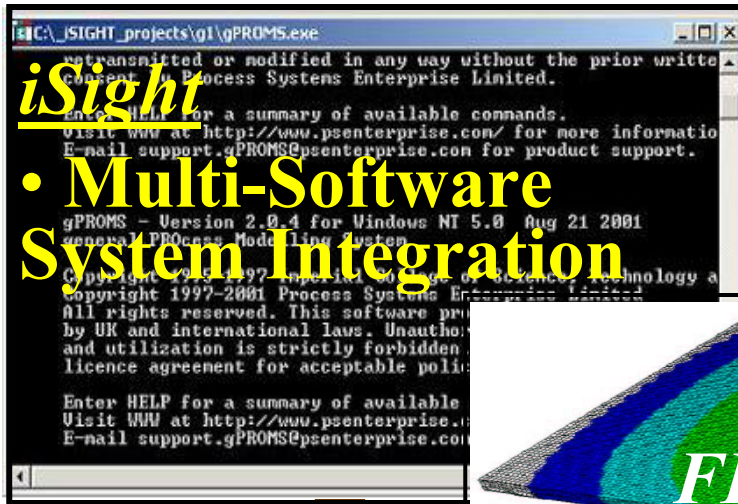
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**PES Modeling &  
System Integration and Analysis**

# Phase-I Comprehensive SOFC-PS Modeling

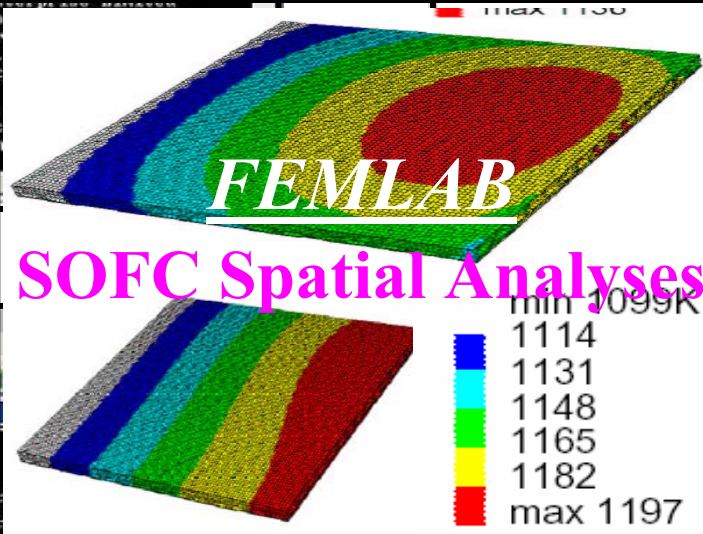
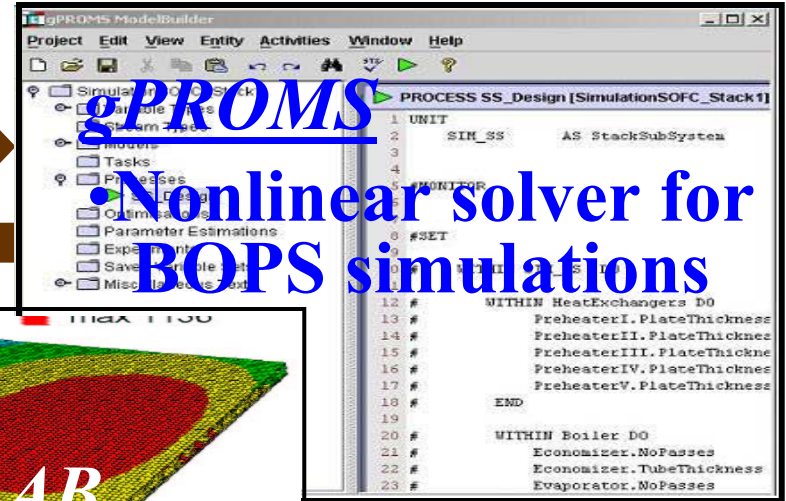
**iSight**

- Multi-Software System Integration



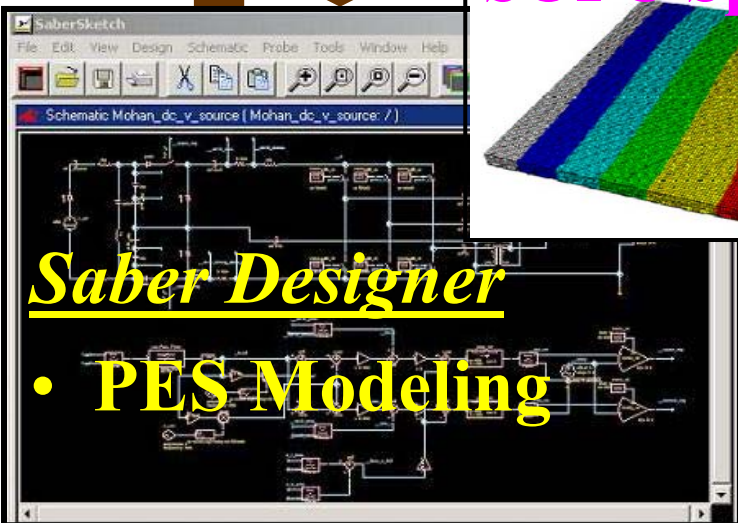
**gPROMS**

- Nonlinear solver for BOPS simulations



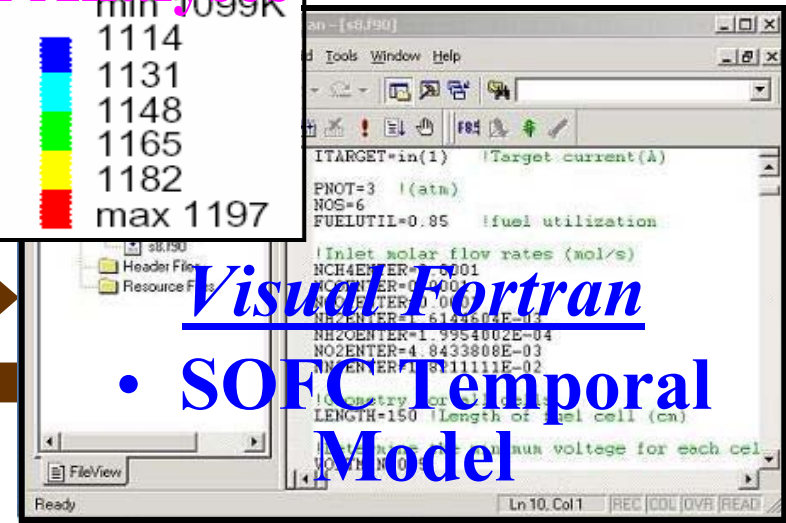
**Saber Designer**

- PES Modeling



**Visual Fortran**

- SOFC Temporal Model



# Modeling Approach for Phase-II

Phase-I Comprehensive SOFC PS Model



Phase-II Modeling Approach

**SIMULINK**

PES + AL Model

S-Function

gPROMS Blockset

**FORTRAN**  
SOFC Model

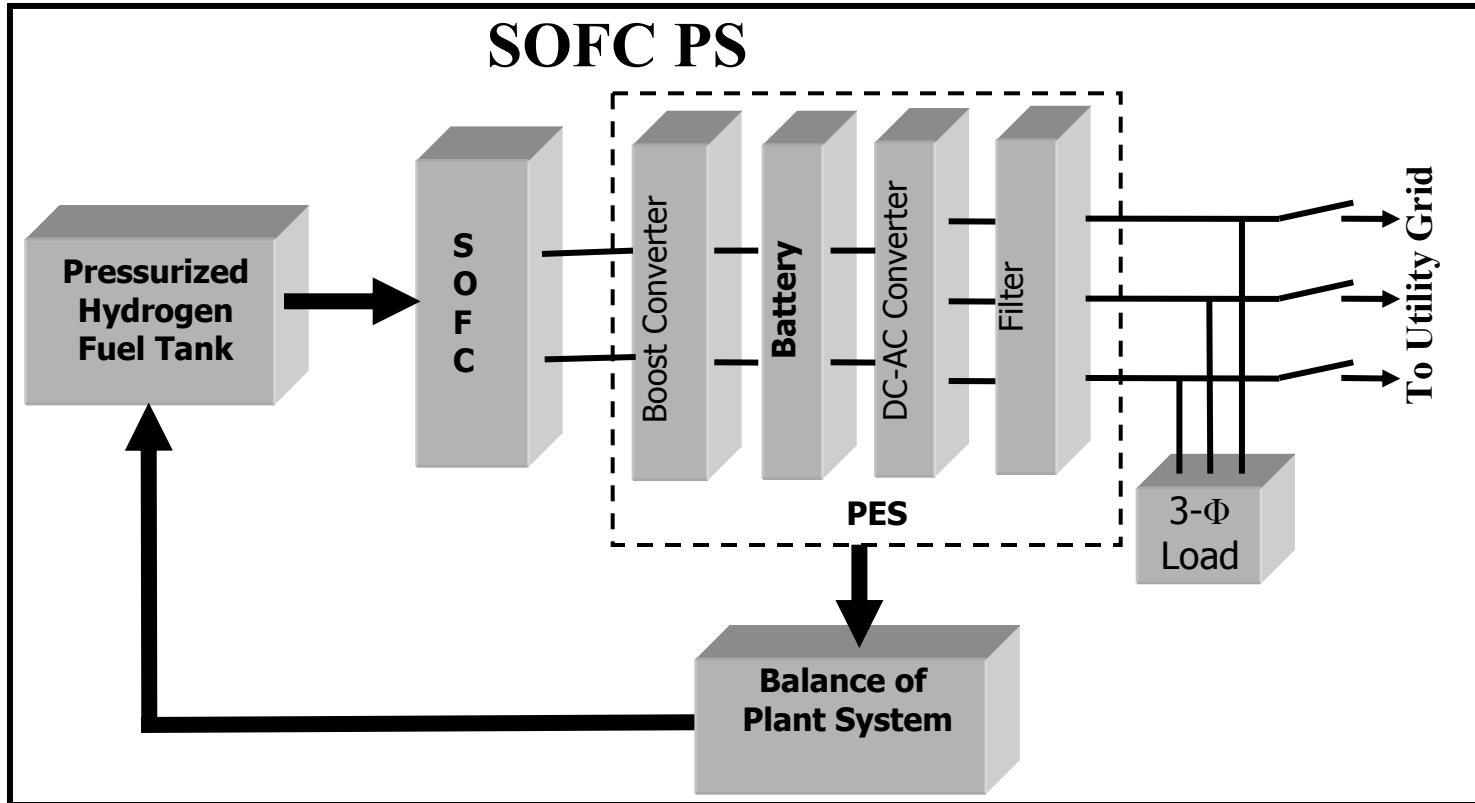
**gPROMS**  
BOPS Model

## Advantages of SIMULINK

- Cost effective
- Easily accessible to members of SECA industrial group
- Can seamlessly integrate with FORTRAN and gPROMS; hence existing SOFC and BOPS models can be used for offline simulation

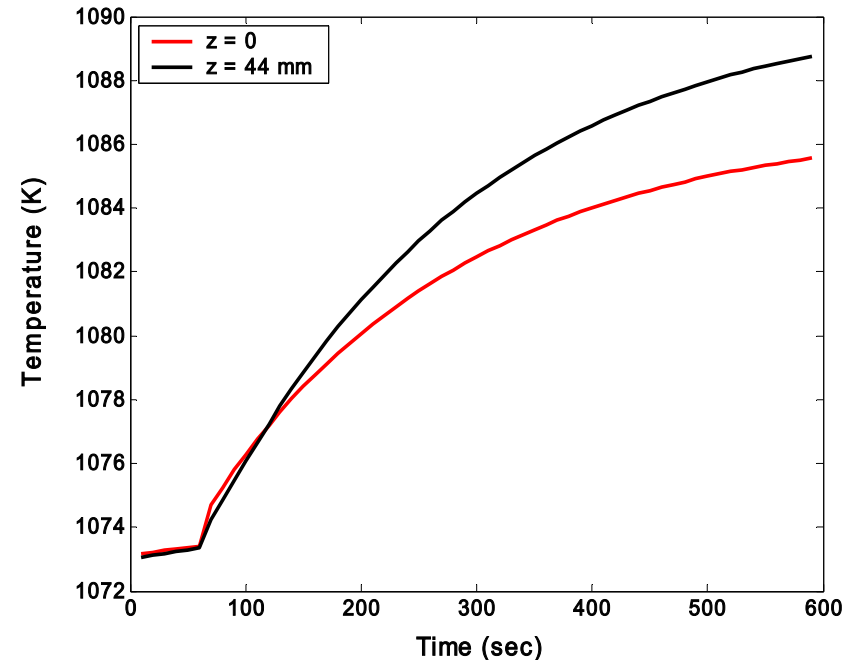
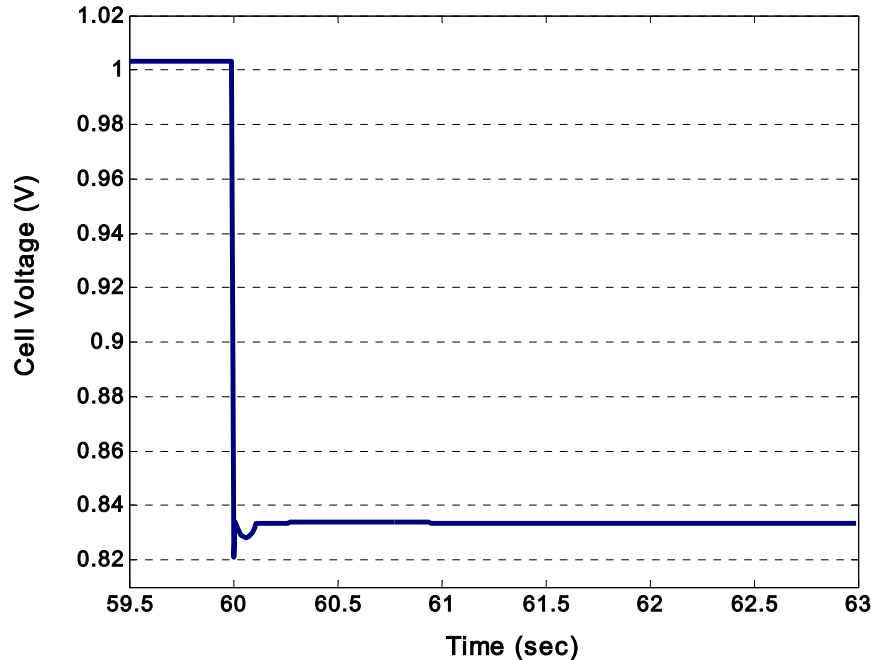
# Load Transient Mitigation

## Energy-Storage Devices



- Energy storage devices to mitigate the effects of load-transients on SOFC
  - Batteries
  - Pressurized-hydrogen storage tanks

# SOFC Response to Load Transients



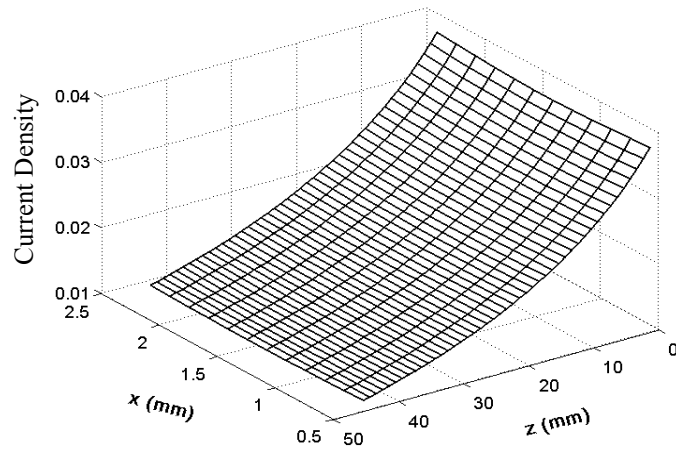
- ❖ Increase in load results in the increases of the current density, which increases the polarization drop in cell, and hence a drop in the cell voltage.
- ❖ Increase in the temperature due to higher thermal energy release resulting from more electro-chemical reactions, i.e.

$$T_{n+1} = \frac{\Delta t}{\rho \cdot C_v \cdot (\Delta V)} q_{total} + T_n$$

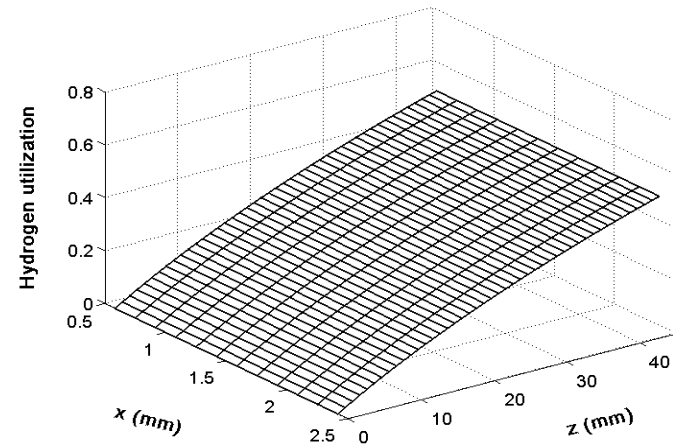
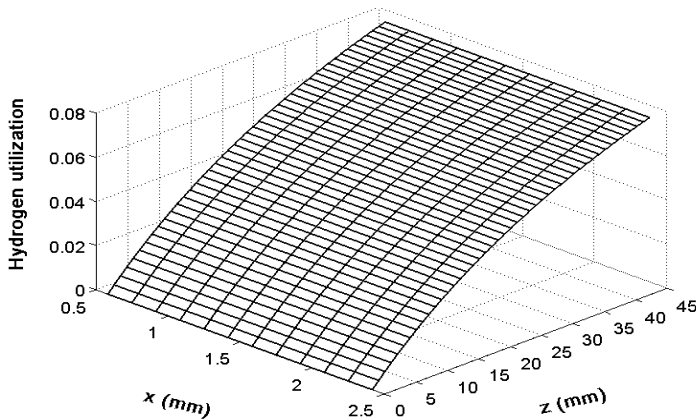
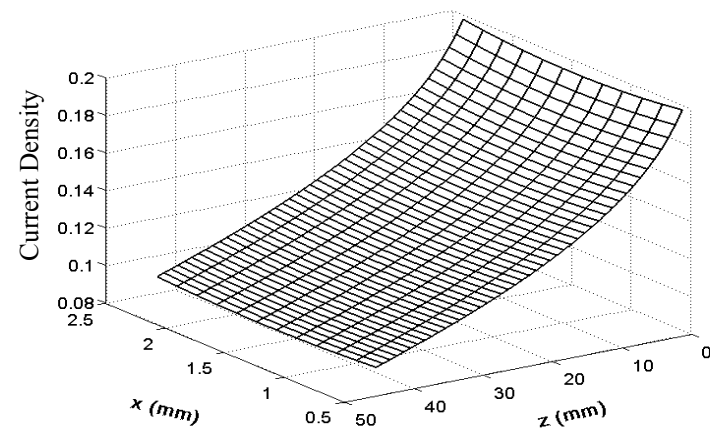
# SOFC Response to Load Transient

## Current Density and Fuel Utilization

### Before Load Transient



### After Load Transient



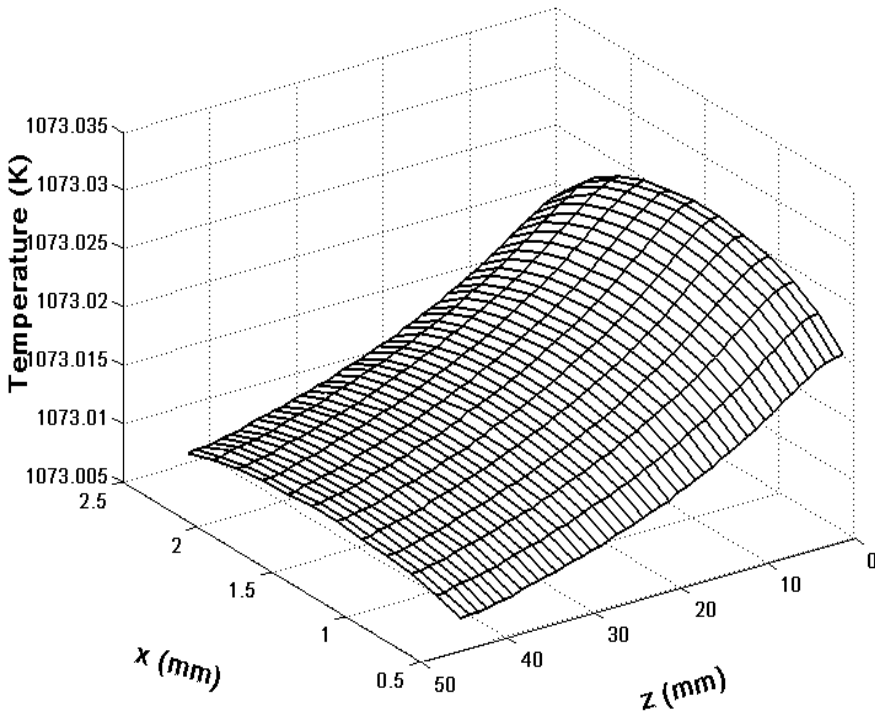
- ❖ A sudden increase in the current density just after the load transient
- ❖ Higher current density increases the fuel utilization drastically just after the load transient



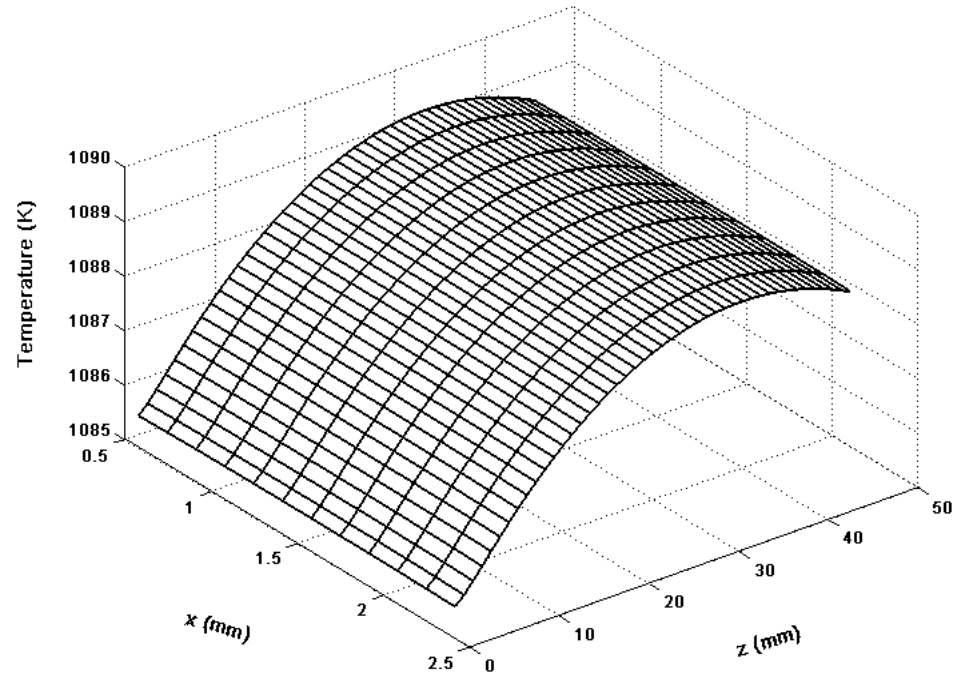
# SOFC Response to Load Transient

## Spatial Temperature Distribution

Before Load Transient



After Load Transient



### • Issues

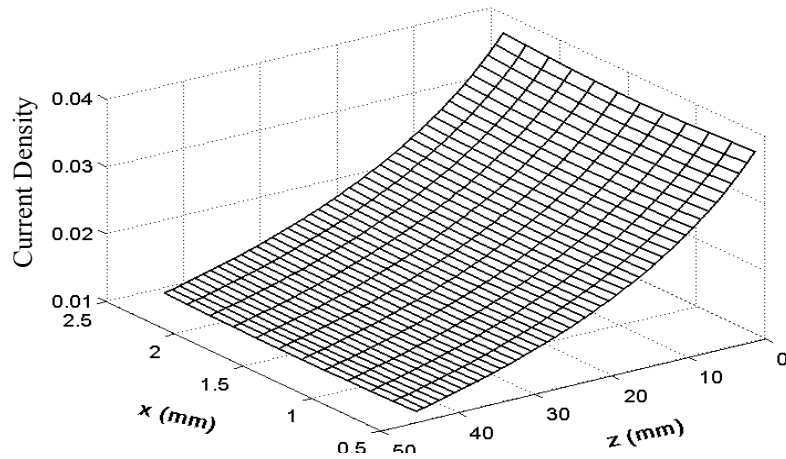
- ❖ Cathode may be subjected to significant stresses (thermal expansion mismatch)
- ❖ Increase in the cleavage strength (comparable to the grain boundary strength)
- ❖ May result in the appearance of inter-granular fracture



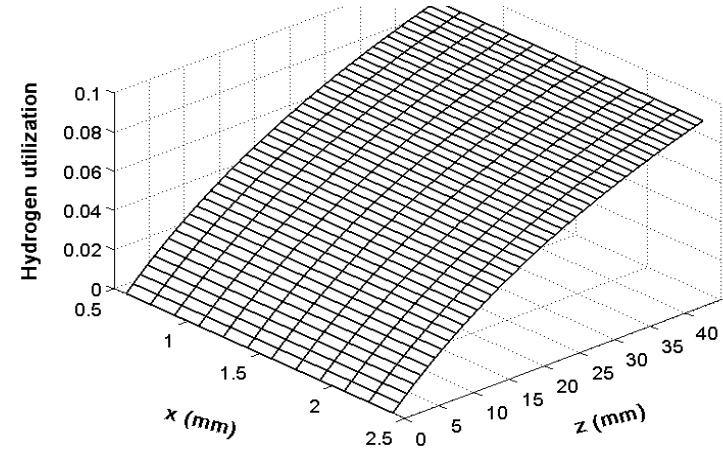
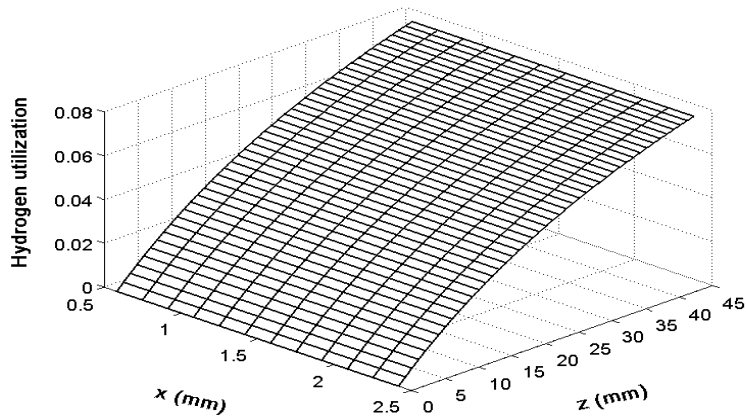
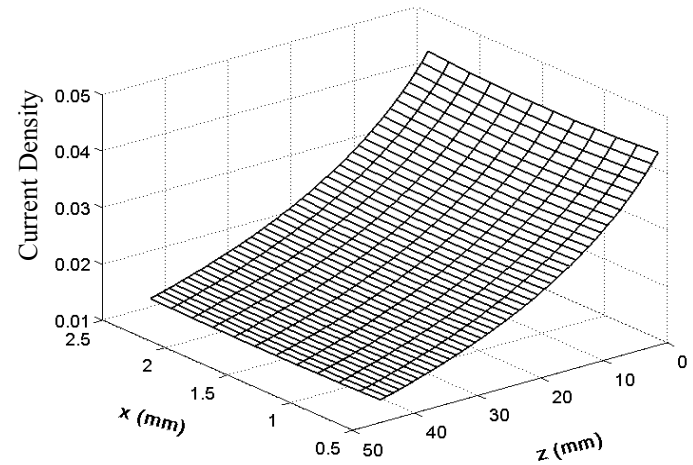
# Load-Transient Mitigation

## Effects of Energy-Buffering Devices

Before Load Transient



After Load Transient

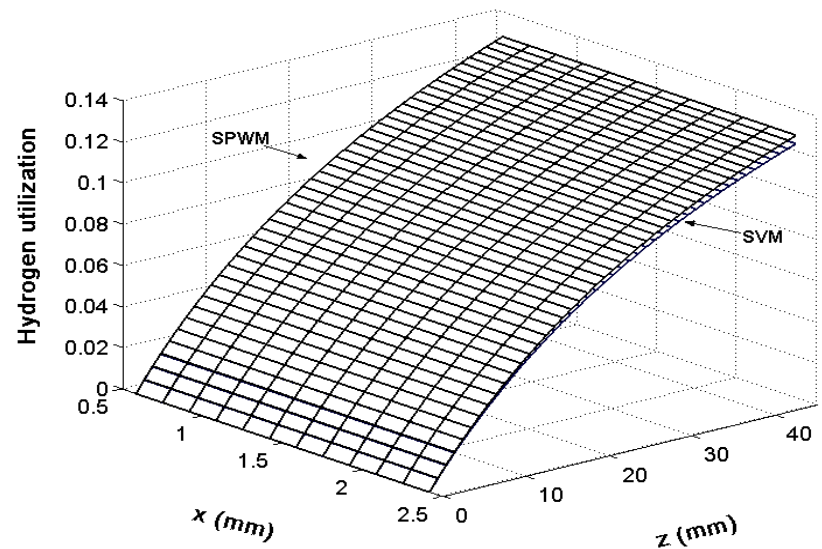
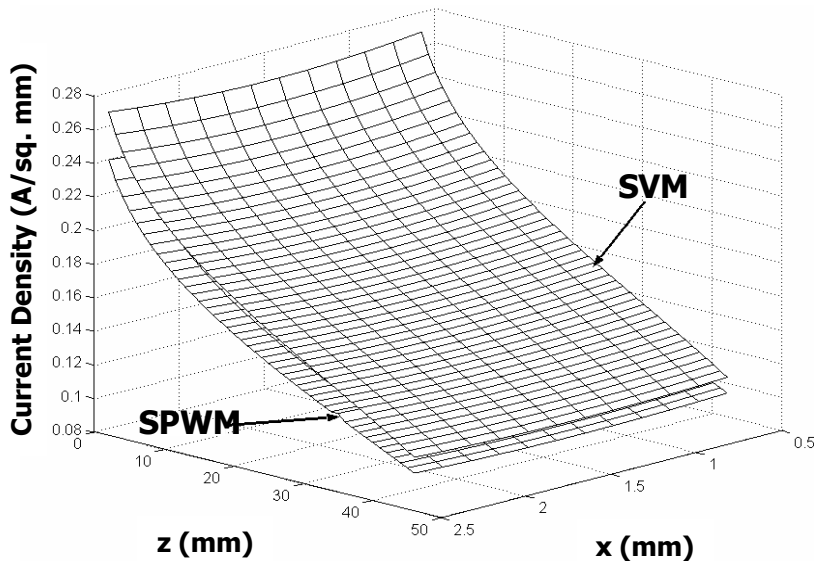
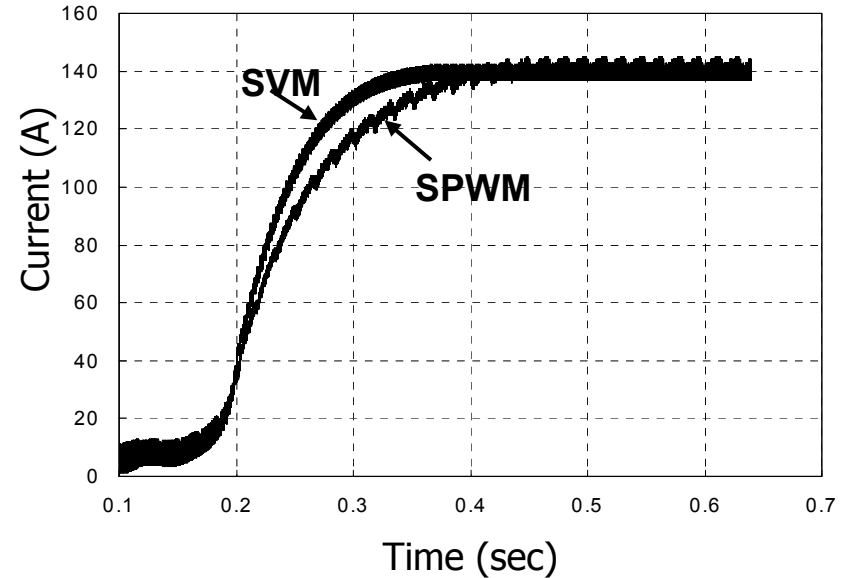


- ❖ Battery provides the required load current during the transient
- ❖ Minimal increase in the current density and in turn minimal increase in the fuel utilization

# Load-Transient Mitigation

## Effect of Advanced Inverter Modulation Techniques

- Space-vector modulation used for the inverter
- Slow boost converter response to prevent immediate change in SOFC energy demands



# Georgia Tech/Ceramatec

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**SOFC**

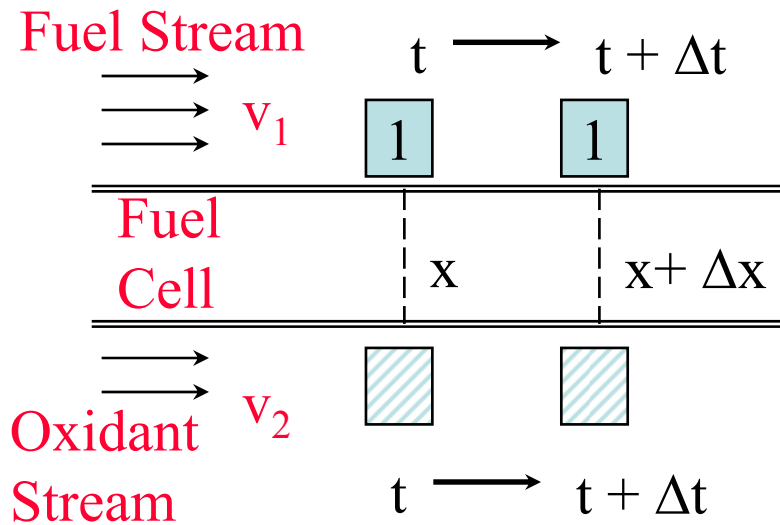
**Modeling and Analysis**

# SOFC Transient Response Time Scales

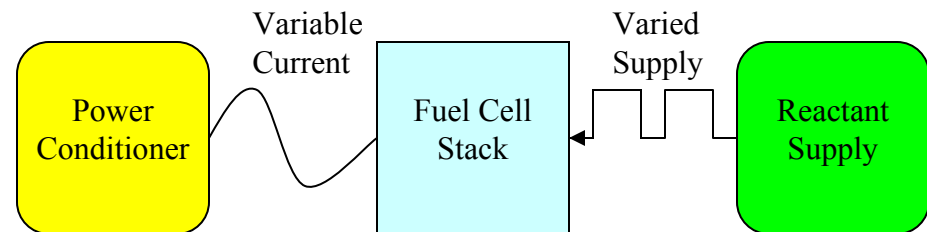
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- Electrochemical ( $\mu\text{sec}$ )
  - Gas phase phenomena
  - Diffusion/surface absorption relaxation
- Hydraulic (msec) - Time Scale in Simulink Model
  - Reactant depletion/accumulation effects within electrode
  - Gas flow transit time
- Thermal (ksec)
  - Too slow to notice power electronics transients
    - Startup
    - Load change
- Aging (years)
  - Lifetime degradation
    - Solid state cation interdiffusion/reaction
    - Microstructural coarsening

# Operational Reactant Feed/ Load Variation



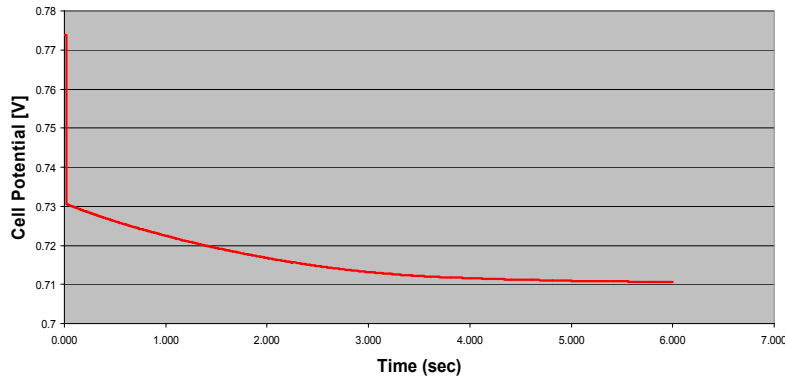
$$\eta_{\text{element}}(t + \Delta t) = \eta_{\text{field}}(x + \Delta x, t + \Delta t)$$



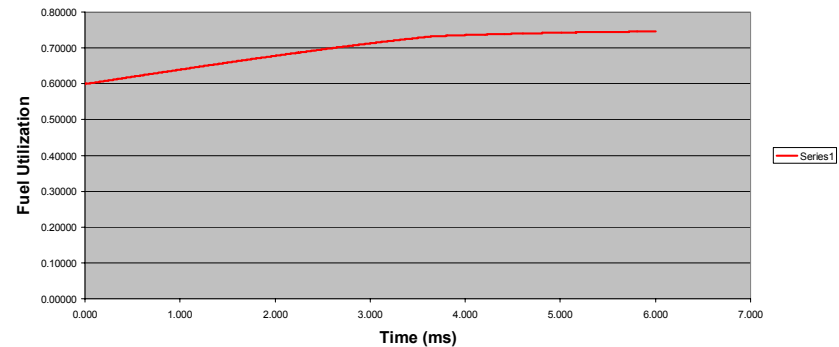
- *Variable cell discretization based upon changing reactants flow rates to maintain msec synchronization*
- *Serial “packets” of time wherein quasi-steady flow supplies are predicated*

# Preliminary Results

**SOFC Voltage Transition**  
300 to 375 mA/cm<sup>2</sup> (25% increase)  
Unslaved



**Fuel Utilization Transition**  
300 to 375 mA/cm<sup>2</sup> (25% increase)  
Unslaved

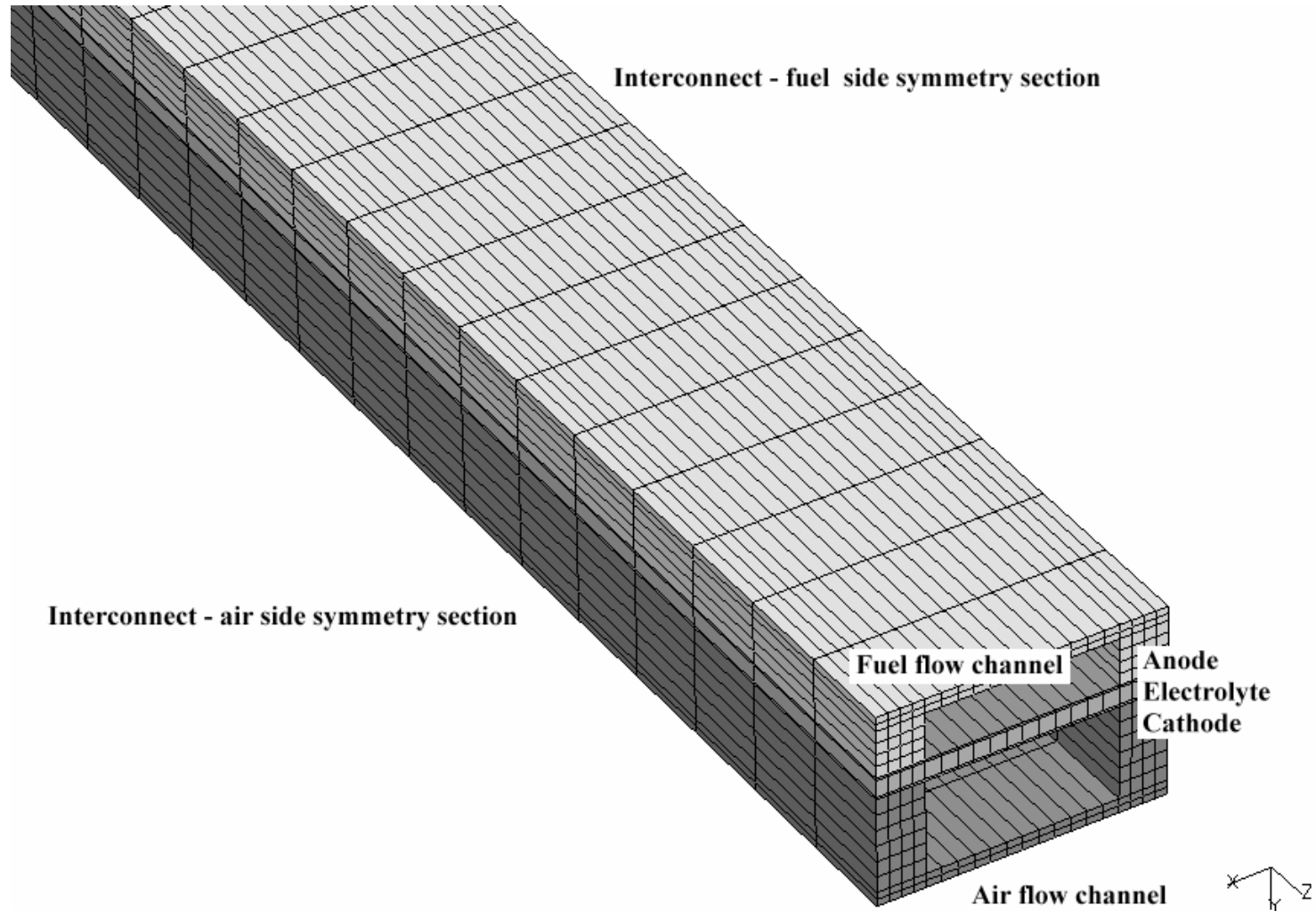


➤ **Plausible transient transition path shown from validated steady state end points**

➤ **Greater attention will be added to the electrode mass transfer transients for higher fidelity modeling (e.g., capturing “undershoot” associated with increases in load current)**

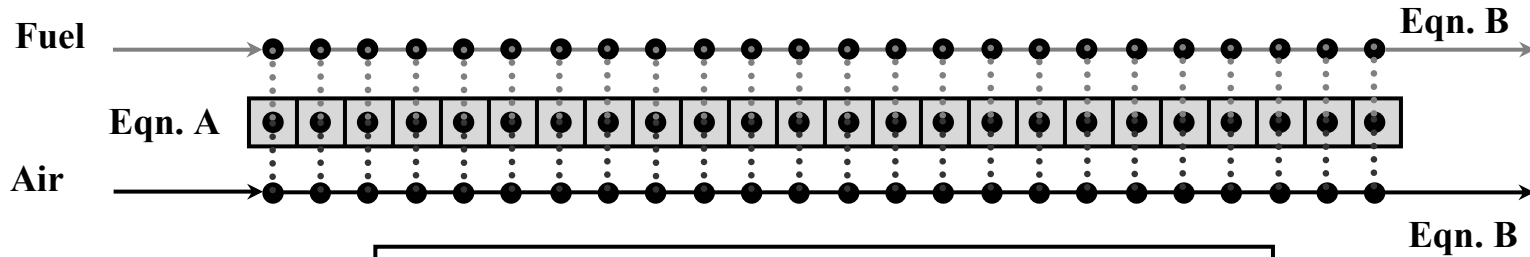
➤ **Matlab/Simulink and FORTRAN developmental environments simultaneously are being accommodated**

# Spatial Effects Resolving Co-flow SOFC Model





# Temporal Effects Resolving Homogenized Spatial Model



Equation A. Heat equation in solid

$$\rho C_p(T) V_f(x) \frac{\partial T}{\partial t} = \frac{\partial}{\partial x} \left[ k V_f(x) \frac{\partial T}{\partial x} \right] + \frac{q''(x)}{A_c}$$

Equation B. Energy transport in gas streams

•Neglecting axial conduction and viscous dissipation

$$\rho C_p \frac{DT}{Dt} = \sum_{i=1}^{nsp} \bar{H}_i \frac{r_i}{m_i} + q(x)$$

$$\bar{H} = 3.5 RT, \text{ For an ideal diatomic gas}$$

$$\frac{DT}{Dt} = \frac{\partial T}{\partial t} + v \frac{\partial T}{\partial x}, \text{ For a 1-D scalar}$$

$$dq_g(x) = h_c P (T_s(x) - T_g(x)) dx$$

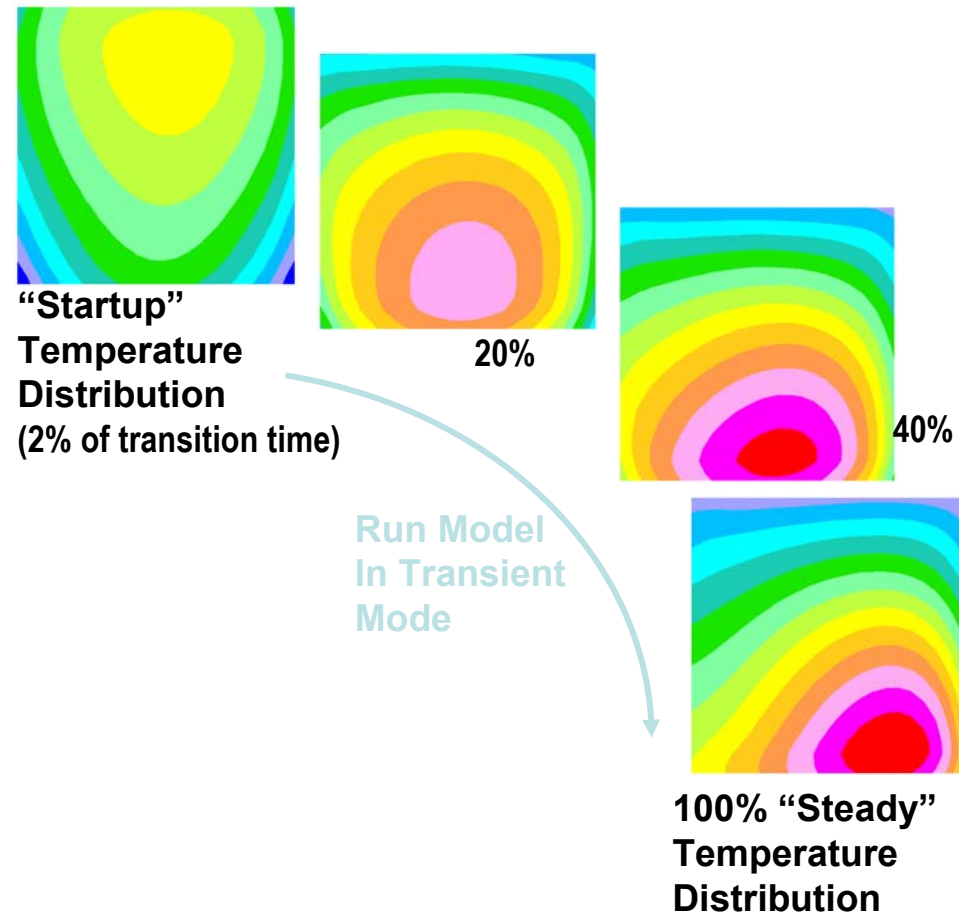
# Thermal-Electrochemical Coupling

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- Electrochemical
  - Temperature dependence
    - Cell ASR,  $k_e$ ,  $E_{rev}$
- Thermal
  - Heat generation/absorption
    - $I^2R$  in current paths
    - Electrochemical heat of reaction ( $T\Delta S$ )
    - Fuel reactions endotherm/exotherm

# Transient Heating: Augment SECA Efforts with Electrochemical “Light-off” Considerations

- Electrochemical light-off is the “kinetic acceleration” occurring during transitional heat-up
- May have significant impact upon cell reliability as a part of thermal cycles and ramp rate
- Electrochemical operating conditions (e.g., load current demand, NOS) provide a unique set of “controls” for this dynamic phenomenon
- Studies to characterize and optimize this intermediate thermal management stage



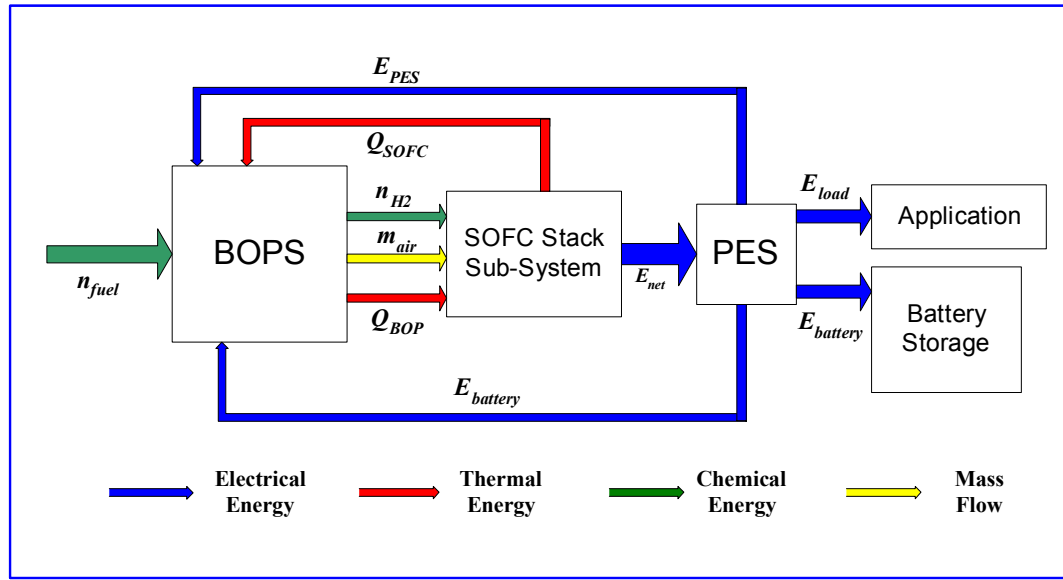
Graphic courtesy of PNNL

# Virginia Polytechnic Institute and State University

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## Balance of Plant Sub-system (BOPS) Modeling and Analysis

# SOFC PS: Balance of Plant Sub-system (BOPS) Phase II Summary



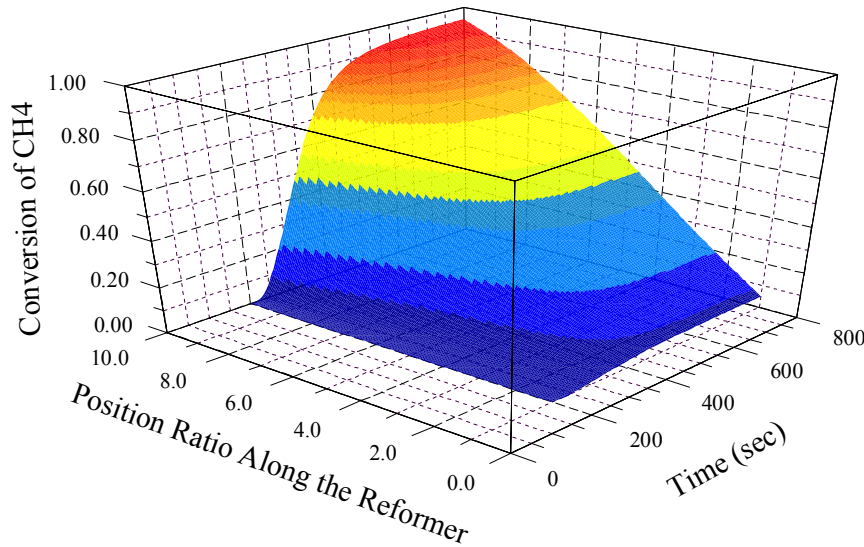
## PHASE II : SYSTEM CONTROL STRATEGIES

### TASKS TO BE PERFORMED

- Analysis of which set of initial “best practice” control strategies to implement for start-up and shut-down
- Modeling and simulation of system-level start-up and shut-down
- Application of large-scale optimization using decomposition to the synthesis/design and operation of the SOFC PS
- Determination of optimal control strategies for normal operation and start-up/shut-down based on their effects on system reliability, performance, and response

# DETAILED MODEL STEAM METHANE REFORMER START-UP RESULTS

### High Pre-Heating



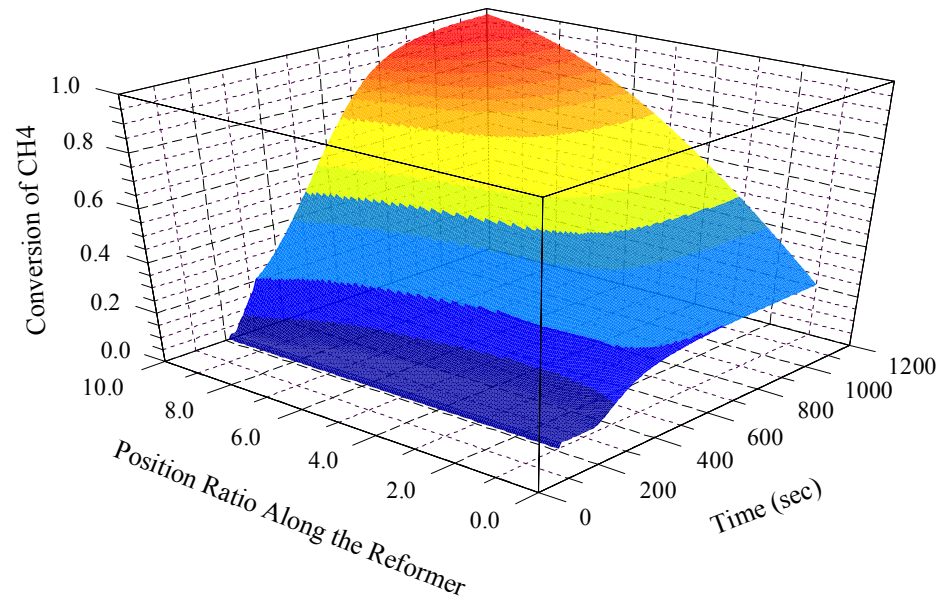
### Steam methane reformer start-up

- Slowest thermal response component of the BOPS
- Faster response. Steady state is reached in 700 sec

### Steam methane reformer start-up for low pre-heating

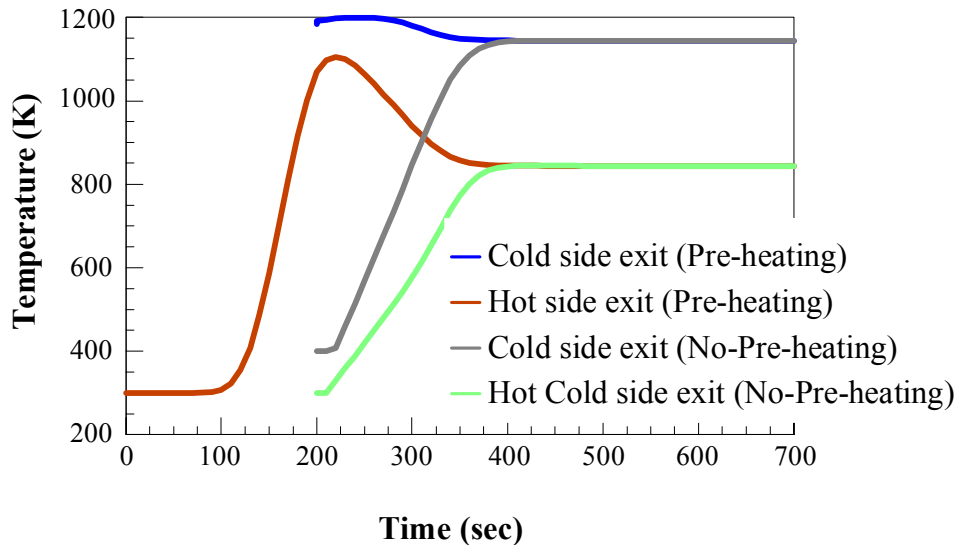
- Slower response. Steady state is reached in 1100 sec
- The chemical response is dependent on the temperature

### Low Pre-Heating



# DETAILED MODEL HEAT EXCHANGER START-UP RESULTS

## Heat Exchanger Start-Up



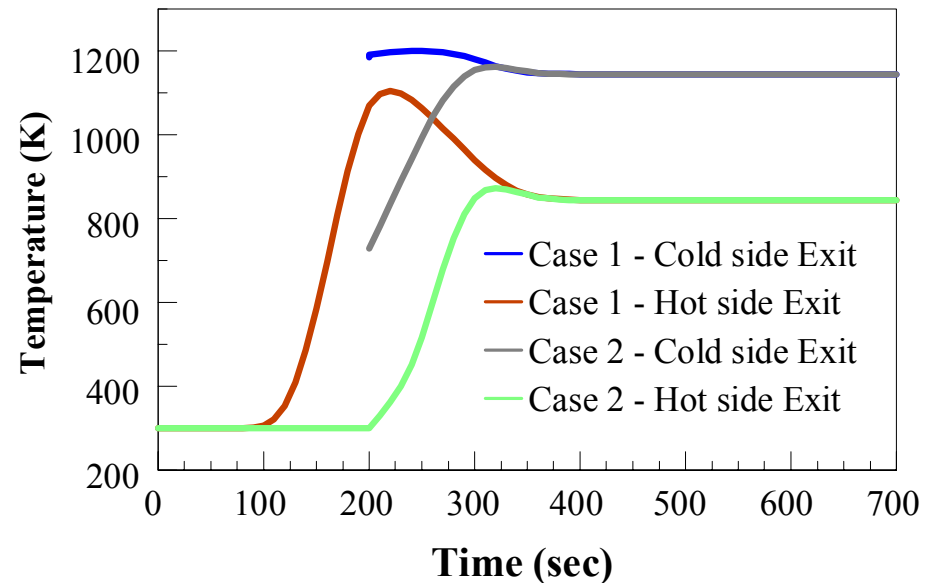
## Comparison between high and no pre-heating

- Pre-heating significantly reduces the time to reach operational temperature

## Comparison between high and low pre-heating

- The Higher the pre-heating, the sooner operational temperatures are reached
- Material temperature gradient constraints are important and should be taken into account

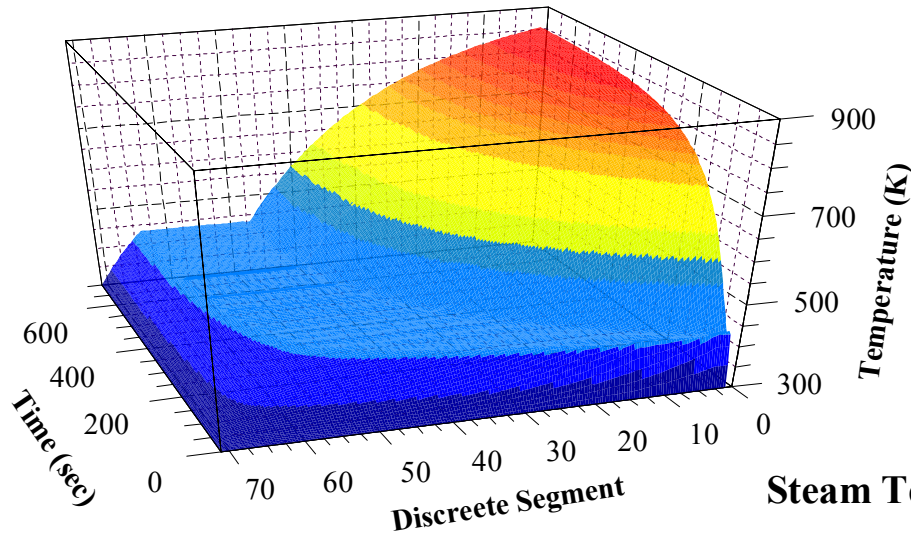
## Heat Exchanger Start-Up





# DETAILED MODEL STEAM GENERATOR START-UP RESULTS

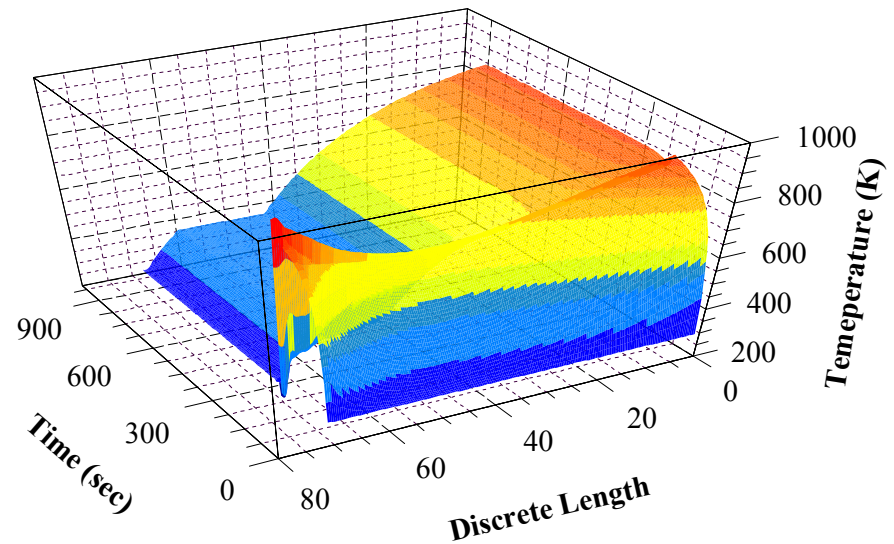
Steam Temperature (Start-Up with No Recirculation)



## Steam generator start-up

- Operational (steady state) temperature (800 °K) is reached within 600 seconds

Steam Temperature (Start-Up with Recirculation)



## Steam generator start-up

- Operational (steady state) temperature (800 °K) is reached immediately after stopping recirculation

# BOPS CONTROL

- Non-Linear State Space Theory:

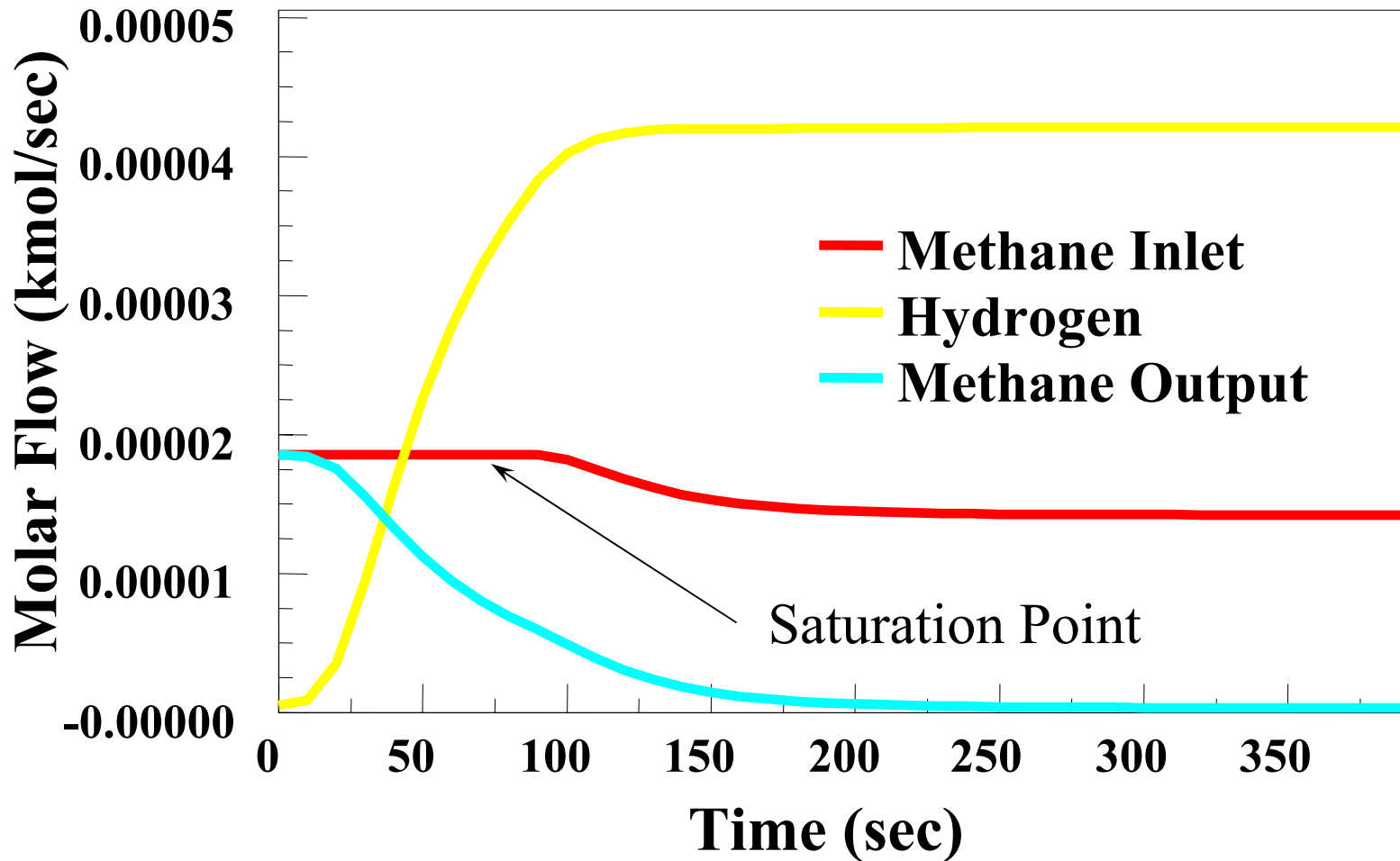
$$\underbrace{J}_{\text{Objective}} = \underbrace{C(\vec{x}, \vec{z})}_{\text{Capital Cost}} + \underbrace{\int_{t_0}^{t_f} f(\dot{\vec{x}}, \vec{x}, \vec{u}, t) dt}_{\text{Operational and Control Cost}} + \underbrace{g(t_f, \vec{x}(t_f))}_{\text{Terminal Cost}}$$

Lagrange Form
Meyer Form

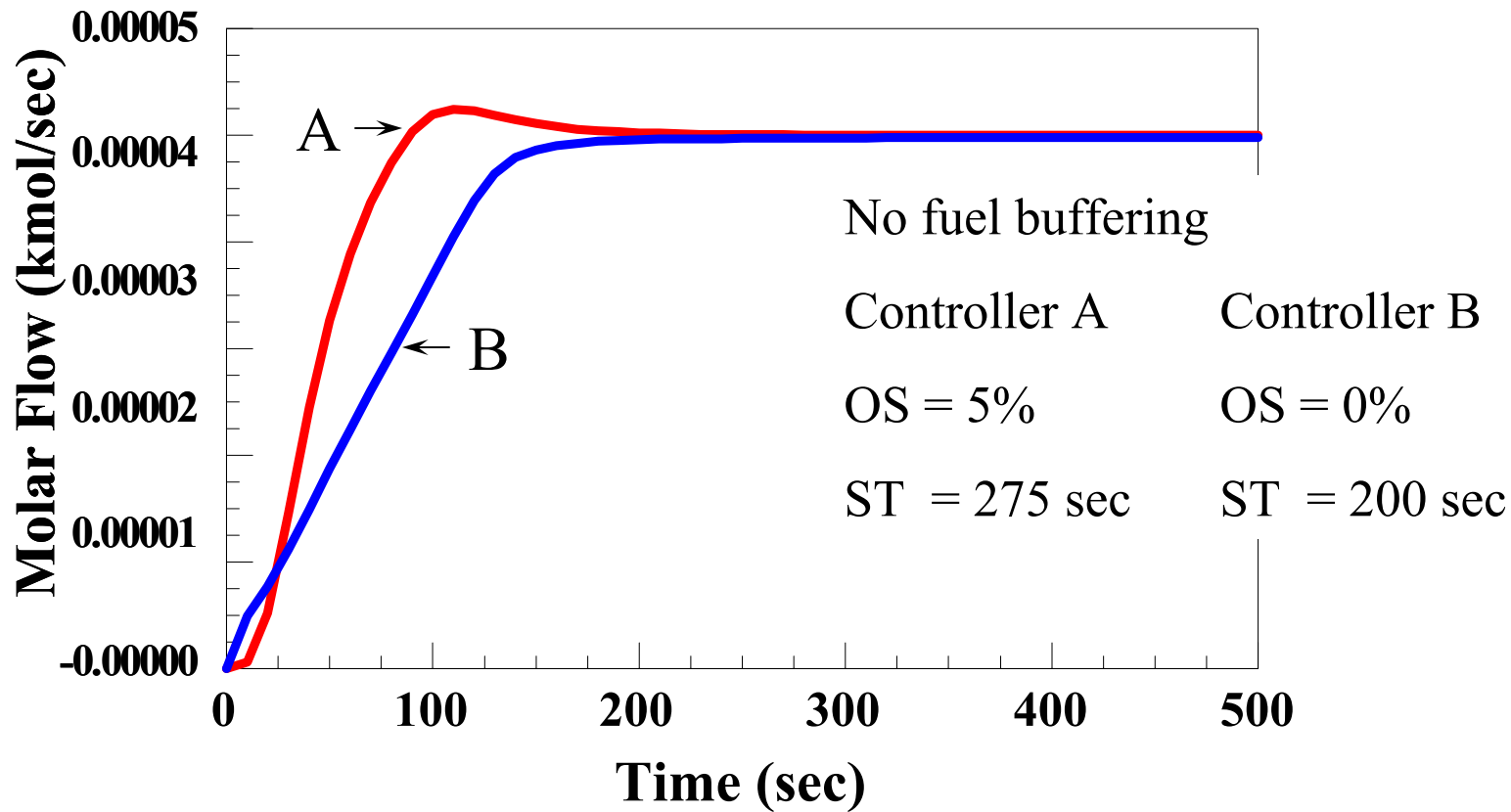
Bolza Form

- Capital and operational costs usually optimized independently of the control and terminal costs. Using ILGO, this optimization problem will be solved as a whole.
- Will develop a PID control model in order to control, e.g., hydrogen production, fuel tank level, and hydrogen flow to the fuel cell stack during start-up and load changes.
- During the optimization phase, both advanced PID and optimal control theory will be used since they are well suited for highly complex, non-linear systems with multiple components. The utility of state space control approaches is limited due to the non-linearities involved.
- Already implemented are controllers for the H<sub>2</sub> flow rate and temperature at the exit of the reformer.

# CONTROL VARIABLE CASE B



# SYSTEM CONTROL



$u(t)$  = Control Variable:  $\dot{m}_{CH_4in}$

$x(t)$  = State Variable: *Power* or  $\dot{m}_{H_2out}$

# Future Work

## Real-Time Simulation

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- Reduction of individual complexity of modules
  - PES model (discontinuous and hybrid nonlinear dynamics)
  - BOPS model (large response times; high order, nonlinear, dynamic)
  - SOFC model (algebraic loops and root convergence)
- Specific executables for PES, BOPS and SOFC for fast interaction
- Execution in MATLAB/ Simulink environment
- Significant decrease in simulation time for the integrated system
  - **Enabling the study of SOFC durability and reliability**
  - **Design of optimized control scheme for the system as a unit for optimized performance, reliability and durability.**

# Future Work

## Planar Solid Oxide Fuel Cell (Planar SOFC)

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- Planar SOFC stack model (electrical, thermal and electrochemical) development, enhancement and model validation
  - Georgia Tech & Cerametec
- Implementation and validation of a comprehensive balance of plant system model (thermodynamic, kinetic, and geometric) and optimal control strategies (*bottoms-up approach*)
  - Virginia Tech & Cerametec
- Development of PES nonlinear topologies (stationary and non-stationary application loads)
  - U of I at Chicago
- System integration and interaction analyses
  - U of I at Chicago

# Future Work

## Development of New Control Strategies

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- Optimal control strategies using a *bottoms-up approach* to improve BOPS response to load transients
- Optimal balance between overall system efficiency, cost, and SOFC stack durability at each load point
- Could lead to the control of each subsystem in such a way that the system responds optimally to any given load
- Greater fidelity as a result of the rigorous simulation of the subsystems and a sufficient consideration of system dynamics